# "Calibeating": Beating Forecasters at Their Own Game

**Sergiu Hart** 

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#### Joint work with

### Dean P. Foster

University of Pennsylvania & Amazon Research NY

Sergiu Hart "Calibration: The Minimax Proof", 1995 [2021]

www.ma.huji.ac.il/hart/publ.html#calib-minmax

Sergiu Hart "Calibration: The Minimax Proof", 1995 [2021]

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www.ma.huji.ac.il/hart/publ.html#calib-minmax
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Dean P. Foster and Sergiu Hart "Smooth Calibration, Leaky Forecasts, Finite Recall, and Nash Dynamics" Games and Economic Behavior 2018

www.ma.huji.ac.il/hart/publ.html#calib-eq

Dean P. Foster and Sergiu Hart "Forecast Hedging and Calibration" Journal of Political Economy 2021

www.ma.huji.ac.il/hart/publ.html#calib-int

Dean P. Foster and Sergiu Hart "Forecast Hedging and Calibration" Journal of Political Economy 2021

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www.ma.huji.ac.il/hart/publ.html#calib-int
```

Dean P. Foster and Sergiu Hart "'Calibeating': Beating Forecasters at Their Own Game" Theoretical Economics 2023

www.ma.huji.ac.il/hart/publ.html#calib-beat

Forecaster says: "The probability of rain tomorrow is p"

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  - for every forecast p: in the days when the forecast was p, the proportion of rainy days equals p

- Forecaster says: "The probability of rain tomorrow is p"
- Forecaster is CALIBRATED if
  - for every forecast p: in the days when the forecast was p, the proportion of rainy days equals p(or: is close to p in the long run)

**CALIBRATION** can be guaranteed

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(no matter what the weather will be)

Foster and Vohra 1994 [publ 1998]

**CALIBRATION** can be guaranteed

- Foster and Vohra 1994 [publ 1998]
- Hart 1995: proof by Minimax Theorem

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**CALIBRATION** can be guaranteed

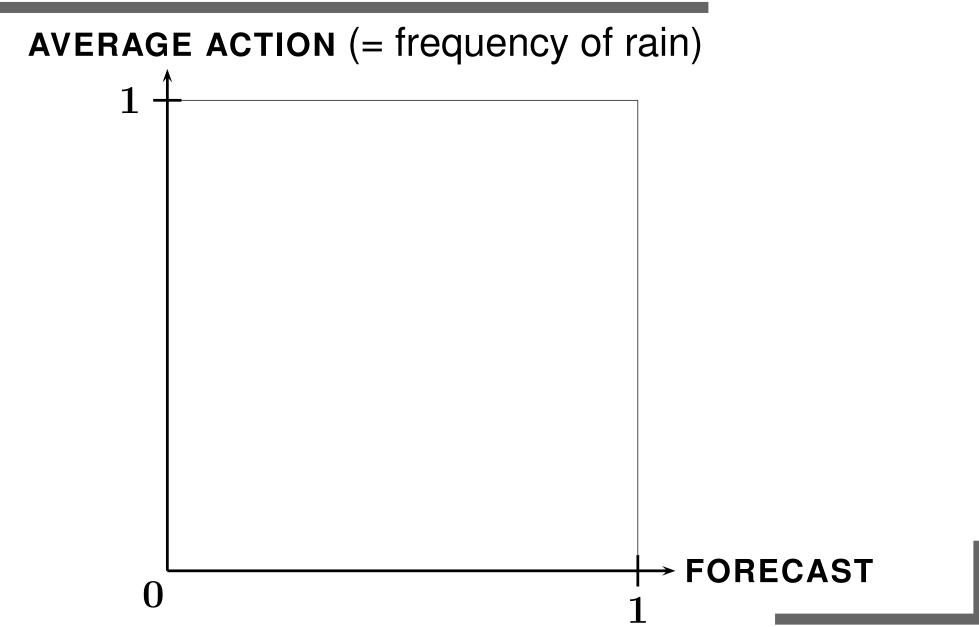
- Foster and Vohra 1994 [publ 1998]
- Hart 1995: proof by Minimax Theorem
- **\_**
- Hart and Mas-Colell 1996 [publ 2000]: procedure by Blackwell's Approachability

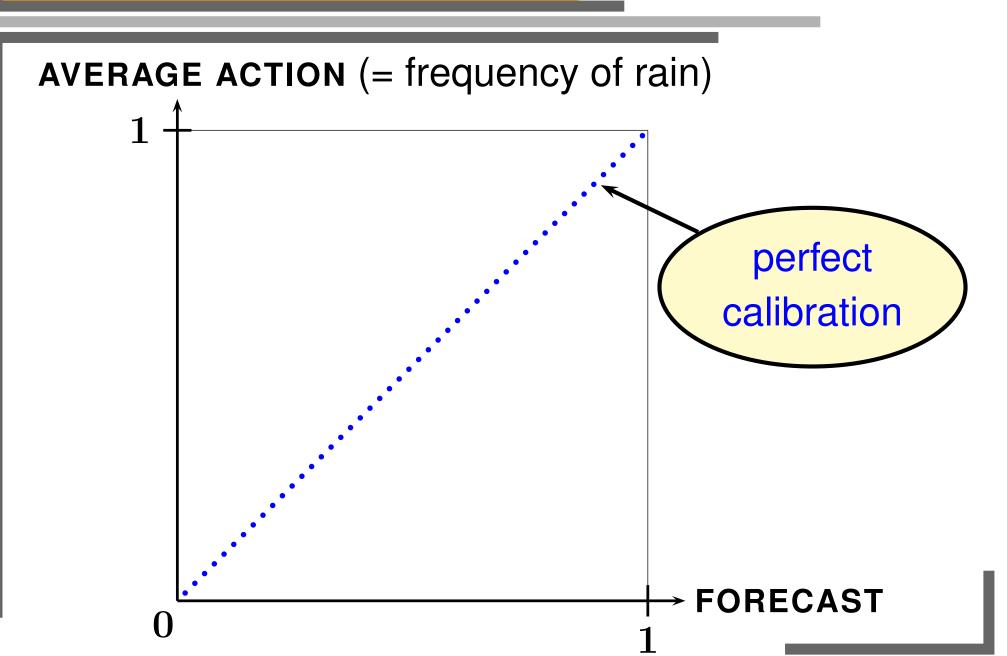
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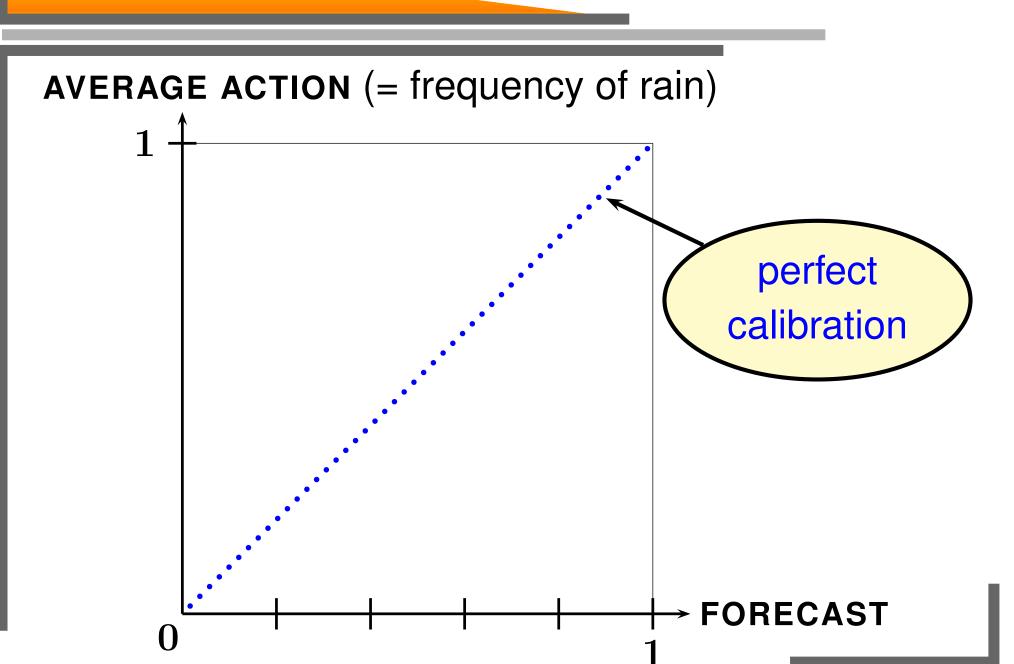
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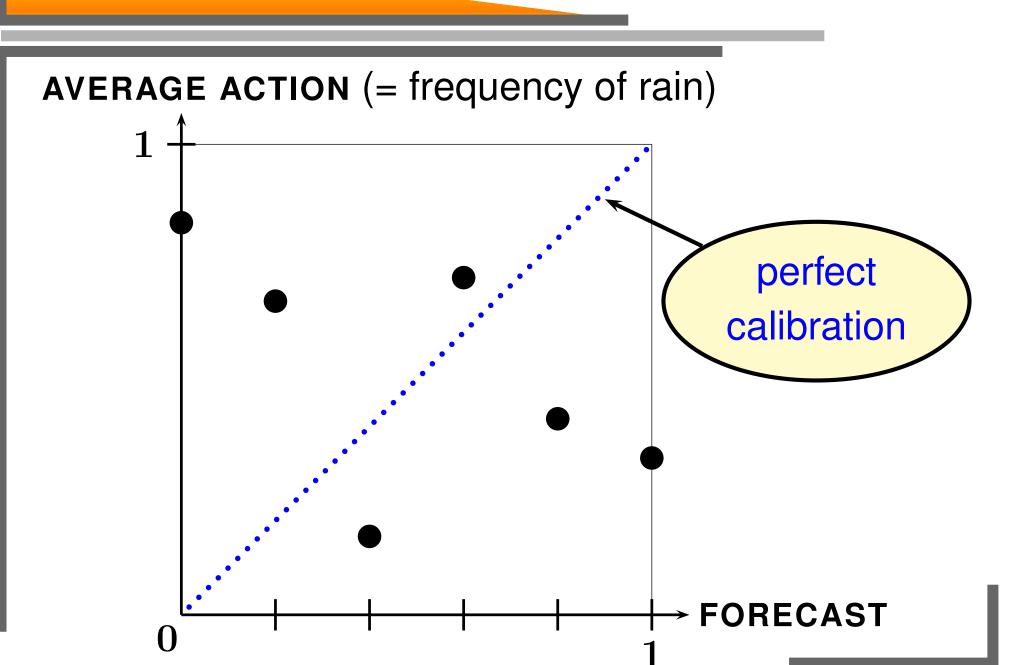
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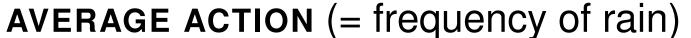
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- Hart and Mas-Colell 1996 [publ 2000]: procedure by Blackwell's Approachability
- Foster 1999: simple procedure
- Foster and Hart 2016 [publ 2021]: simplest procedure, by "Forecast Hedging"

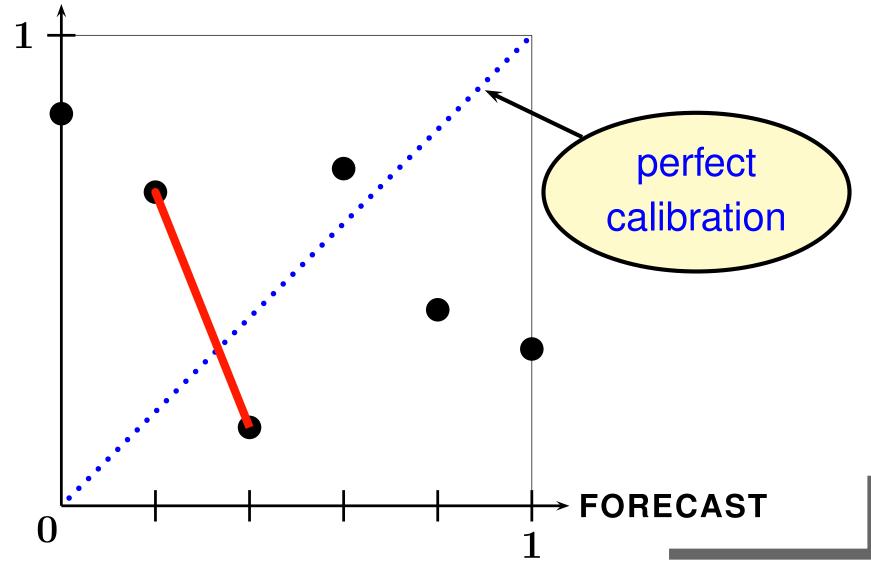


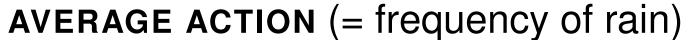


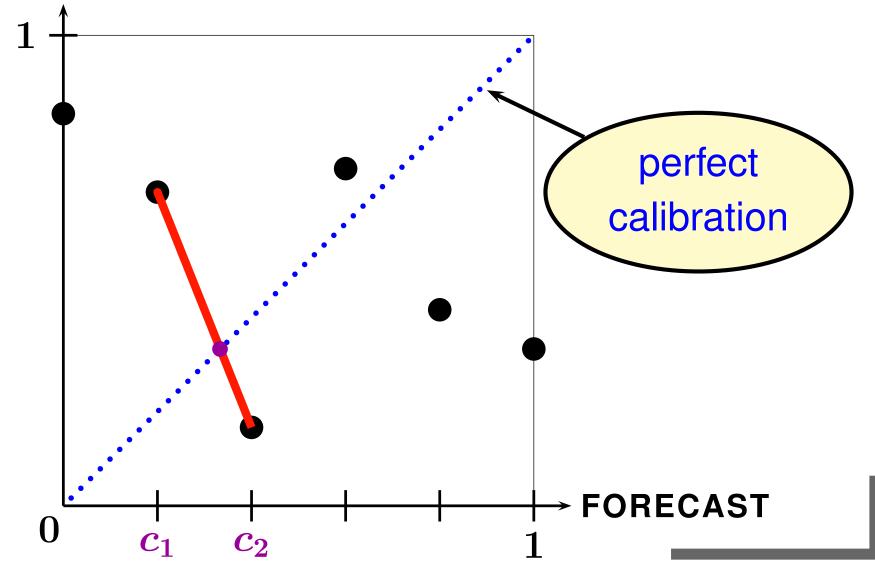






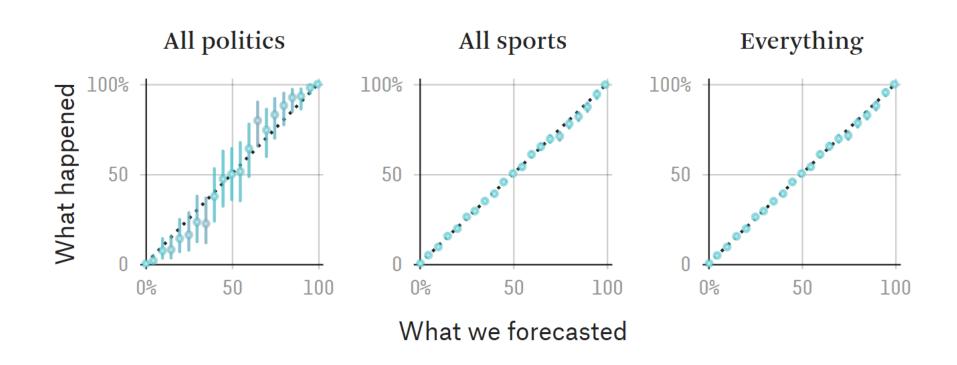






### **Calibration in Practice**

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Calibration plots of FiveThirtyEight.com (as of June 2019)

#### **Calibration** in Practice



**Prediction buckets** 

Calibration plot of ElectionBettingOdds.com (2016 – 2018)

time | 1 | 2 | 3 | 4 | 5 | 6 | ...

time	$oxed{1}$	2	3	4	5	6	
rain	1	0	1	0	1	0	

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0

F2: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0 IN-BIN VARIANCE = 0

F2: CALIBRATION = 0

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: CALIBRATION = 0 IN-BIN VARIANCE = 0

F2: CALIBRATION = 0 IN-BIN VARIANCE =  $\frac{1}{4}$ 

•  $a_t = action at time t$ 

- $m{a}_t = ext{action at time } t$
- $c_t$  = forecast at time t

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$$ar{a}(x) = rac{\sum_{t=1}^T \mathbf{1}_x(oldsymbol{c}_t)\,a_t}{\sum_{t=1}^T \mathbf{1}_x(oldsymbol{c}_t)}$$

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$$\mathcal{K} = rac{1}{T} \sum_{t=1}^T \| oldsymbol{c}_t - ar{a}(oldsymbol{c}_t) \|^2$$

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$$\mathcal{R} = rac{1}{T} \sum_{t=1}^T \|a_t - ar{a}(oldsymbol{c}_t)\|^2$$

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**BRIER** = REFINEMENT + CALIBRATION

Proof.

$$\mathbb{E}[(X-c)^2] = \mathbb{V}ar(X) + (ar{X}-c)^2$$

where c is a constant and  $oldsymbol{X}$  is a random variable with  $ar{oldsymbol{X}} = \mathbb{E}[oldsymbol{X}]$ 

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F1: 
$$\mathcal{K} = 0$$
  $\mathcal{R} = 0$ 

F2: 
$$K = 0$$
  $R = \frac{1}{4}$ 

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
F1	100%	0%	100%	0%	100%	0%	
F2	50%	50%	50%	50%	50%	50%	

F1: 
$$\mathcal{K} = 0$$
  $\mathcal{R} = 0$   $\mathcal{B} = 0$ 

F2: 
$$K = 0$$
  $R = \frac{1}{4}$   $B = \frac{1}{4}$ 

## **Testing experts:**

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**✓ Brier** score

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- **✓ Brier** score
- X CALIBRATION score

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**LOW** REFINEMENT SCORE

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Can one GAIN CALIBRATION without LOSING "EXPERTISE"?

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ullet Can one get  $\mathcal K$  to 0 without increasing  $\mathcal R$ ?

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- But: CALIBRATION procedures ignore whatever "EXPERTISE" one has

#### **Question:**

Can one GAIN CALIBRATION without LOSING "EXPERTISE"?

- Can one get K to 0 without increasing R?
- Can one decrease  $\mathcal{B} = \mathcal{R} + \mathcal{K}$  by  $\mathcal{K}$ ?

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$$\Rightarrow \mathcal{K}' = 0 \quad \mathcal{R}' = \mathcal{R}$$

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$$\Rightarrow \mathcal{K}' = 0$$
  $\mathcal{R}' = \mathcal{R}$   $\mathcal{B}' = \mathcal{B} - \mathcal{K}$ 

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• IN RETROSPECT / OFFLINE (when the  $\bar{a}(c)$  are known)

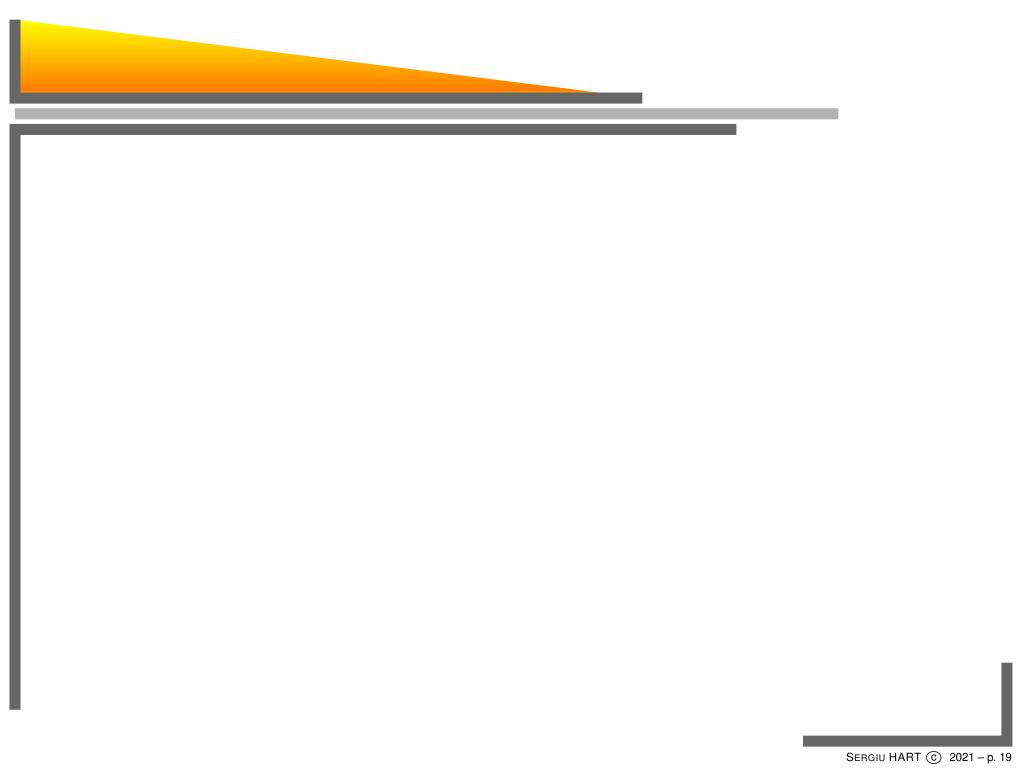
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$$\Rightarrow$$
  $\mathcal{K}^{'}=0$   $\mathcal{R}^{'}=\mathcal{R}$   $\mathcal{B}^{'}=\mathcal{B}-\mathcal{K}$ 

• IN RETROSPECT / OFFLINE (when the  $\bar{a}(c)$  are known)

#### **Question:**

Can one do this **ONLINE**?



• Consider a forecasting sequence  $b_t$  (in a [finite] set B)

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$$\mathcal{B}_T^{\mathrm{c}} \leq \mathcal{B}_T^{\mathrm{b}} - \mathcal{K}_T^{\mathrm{b}} + \mathrm{o}(1) \quad \mathrm{as} \ T \to \infty$$

for ALL sequences  $a_t$  and  $b_t$  (uniformly)

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 $oldsymbol{c}$  "BEATS" b by b 's CALIBRATION score

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$$|\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}| = \mathcal{R}^{b}$$

c "BEATS" b by b's CALIBRATION score

GUARANTEED for ALL sequences of actions and forecasts

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
b	80%	40%	80%	40%	80%	40%	

time	1	2	3	4	5	6	
rain	1	0	1	0	1	0	
b	80%	40%	80%	40%	80%	40%	
		•		•		•	1

b: 
$$K^{\rm b} = 0.1$$
  $R^{\rm b} = 0$   $R^{\rm b} = 0.1$ 

$$\mathcal{R}^{\mathrm{b}}=0$$

$$\mathcal{B}^{\mathrm{b}}=0.1$$

time	1	2	3	4	5	6	•••
rain	1	0	1	0	1	0	
$\overline{b}$	80%	40%	80%	40%	80%	40%	
c	100%	0%	100%	0%	100%	0%	

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$$K^{b} = 0.1$$
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$$\mathcal{R}^{\mathrm{b}} = 0$$

$${\cal B}^{\rm b} = 0.1$$

c: 
$$\mathcal{K}^{c} = 0$$
  $\mathcal{R}^{c} = 0$   $\mathcal{B}^{c} = 0$ 

$$\mathcal{R}^{\mathrm{c}} = 0$$

$$\mathcal{B}^{c}=0$$

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$$c$$
 calibeats  $b$ :  $\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}$ 

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c: 
$$\mathcal{K}^{c} = 0$$
  $\mathcal{R}^{c} = 0$   $\mathcal{B}^{c} = 0$ 

c calibeats b:  $\mathcal{B}^{\mathrm{c}} \leq \mathcal{B}^{\mathrm{b}} - \mathcal{K}^{\mathrm{b}} = \mathcal{R}^{\mathrm{b}}$ 

(that was easy ...)

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Can one CALIBEAT in general, non-stationary, situations?

(that was easy ...)

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Weather is arbitrary and not stationary

(that was easy ...)

- Weather is arbitrary and not stationary
- Forecasts of b are arbitrary

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- **Binning of** b is not perfect ( $\mathcal{R}^{b} > 0$ )

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- Weather is arbitrary and not stationary
- Forecasts of b are arbitrary
- **Binning of** b is not perfect ( $\mathcal{R}^{b} > 0$ )
- Bin averages do not converge
- ONLINE
- GUARANTEED (even against adversary)

### **Theorem**

There exists a **CALIBEATING** procedure

# A Way to Calibeat

## A Way to Calibeat

### **Theorem**

The procedure

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

**GUARANTEES b-CALIBEATING** 

## A Simple Way to Calibeat

### **Theorem**

The procedure

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

**GUARANTEES b-CALIBEATING** 

Forecast the average action of the current *b*-forecast

$$\mathbb{V} ext{ar} \; = \; rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
ight\|^2$$

$$\mathbb{V} ext{ar} \ = \ rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T\|^2 \ = \ rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \|x_t - ar{x}_{t-1}\|^2$$

$$\mathbb{V} ext{ar} \ = \ rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T^T\|^2 \ = \ rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \|x_t - ar{x}_{t-1}^T\|^2$$

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$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left( 1 - rac{1}{t} 
ight) \left\| x_t - ar{x}_{t-1} 
ight\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_{t-1} 
ight\|^2 - \mathrm{o}(1) \end{array}$$

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(\*) 
$$o(1) = O\left(\frac{1}{T}\sum_{t=1}^{T} \frac{1}{t}\right) = O\left(\frac{\log T}{T}\right)$$

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \left\| x_t - ar{x}_T 
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## **Proof: "Online Variance"**

$$egin{array}{lll} \mathbb{V} \mathrm{ar} &=& rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_T\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \left(1 - rac{1}{t}
ight) \|x_t - ar{x}_{t-1}\|^2 \ &=& rac{1}{T} \sum_{t=1}^{T} \|x_t - ar{x}_{t-1}\|^2 - \mathrm{o}(1) \ &=& \widetilde{\mathbb{V} \mathrm{ar}} & - \mathrm{o}(1) \end{array}$$

## **Proof: "Online Variance"**

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$

## **Proof: "Online Refinement"**

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$
 $\mathcal{R}^\mathrm{b} = \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1)$ 

## **Proof: "Online Refinement"**

$$egin{array}{lll} \mathbb{V}\mathrm{ar} &=& \widetilde{\mathbb{V}}\mathrm{ar} - \mathrm{o}(1) \ & \mathcal{R}^\mathrm{b} &=& \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1) \ &=& rac{1}{T} \sum_{t=1}^T \|a_t - ar{a}_{t-1}(b_t)\|^2 - \mathrm{o}(1) \end{array}$$

## **Proof: "Online Refinement"**

$$\mathbb{V}\mathrm{ar} = \widetilde{\mathbb{V}\mathrm{ar}} - \mathrm{o}(1)$$
 $\mathcal{R}^\mathrm{b} = \widetilde{\mathcal{R}}^\mathrm{b} - \mathrm{o}(1)$ 
 $= \underbrace{\frac{1}{T} \sum_{t=1}^{T} \|a_t - \bar{a}_{t-1}(b_t)\|^2 - \mathrm{o}(1)}_{= \underline{c}_t = \bar{a}_{t-1}(b_t)}$ 

### **Theorem**

$$\left[ oldsymbol{c}_t = ar{a}_{t-1}^{\mathrm{b}}(b_t) 
ight]$$

#### **GUARANTEES b-CALIBEATING:**

$$\mathcal{B}^{c} \leq \mathcal{B}^{b} - \mathcal{K}^{b}$$

## **Self-Calibeating**

### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{b}}(b_t)$$

#### **GUARANTEES b-CALIBEATING:**

$$\mathcal{B}^{c} < \mathcal{B}^{b} - \mathcal{K}^{b}$$

#### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{c}}(oldsymbol{c}_t)$$

#### **GUARANTEES C-CALIBEATING:**

$$\mathcal{B}^{c} < \mathcal{B}^{c} - \mathcal{K}^{c}$$

## **Self-Calibeating**

### **Theorem**

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#### **GUARANTEES b-CALIBEATING:**

$$\mathcal{B}^{\mathrm{c}} \leq \mathcal{B}^{\mathrm{b}} - \mathcal{K}^{\mathrm{b}}$$

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$$\mathcal{B}^{c} \leq \mathcal{B}^{c} - \mathcal{K}^{c}$$
  
 $\Leftrightarrow \mathcal{K}^{c} = 0$ 

# **Self-Calibeating** = Calibrating

### **Theorem**

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#### **GUARANTEES b-CALIBEATING:**

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### **Theorem**

$$oldsymbol{c}_t = ar{a}_{t-1}^{ ext{c}}(oldsymbol{c}_t)$$

#### **GUARANTEES CALIBRATION:**

$$\beta^{c} \leq \beta^{c} - \mathcal{K}^{c}$$

$$\Leftrightarrow \mathcal{K}^{c} = 0$$

How do we get  $c_t$  "close to"  $\bar{a}_{t-1}(c_t)$ ?

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- $m{Q} \subset \mathbb{R}^m$  compact convex
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**Theorem** There exists a probability distribution  ${\color{red}P}$  on the  $\delta$ -grid  ${\color{red}D}$  of  ${\color{red}C}$  such that

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$$\mathbb{E}_{\boldsymbol{x} \sim \boldsymbol{P}} \left[ \left\| \boldsymbol{v} - \boldsymbol{x} \right\|^2 - \left\| \boldsymbol{v} - \boldsymbol{g}(\boldsymbol{x}) \right\|^2 \right] \leq \delta^2 \quad \forall \boldsymbol{v} \in \boldsymbol{C}$$

### Stochastic "Fixed Point"

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Obtained by solving a Minimax problem (LP)

## **Outgoing Minimax (FH)**

How do we get  $c_t$  "close to"  $\bar{a}_{t-1}(c_t)$ ?

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### Stochastic "Fixed Point" (FH)

**Theorem** There exists a probability distribution  ${\it P}$  on the  $\delta$ -grid  ${\it D}$  of  ${\it C}$  such that

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- Obtained by solving a MINIMAX problem (LP)
- Moreover: solving a FIXED POINT problem yields a probability distribution  $\eta$  that is **ALMOST DETERMINISTIC**: its support is included in a ball of size  $\delta$

#### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBRATION** 

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*Proof.* Self-calibeating + Outgoing Minimax

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*Proof.* Self-calibeating + Outgoing Minimax

Note.  $\delta$ -CALIBRATION

#### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBEATING** 

#### **Theorem**

There is a stochastic procedure that **GUARANTEES CALIBEATING** and **CALIBRATION** 

#### **Theorem**

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*Proof.* Calibeat the **joint** binning of b and c, by the Outgoing Minimax theorem

#### **Theorem**

There is a *deterministic* procedure that **GUARANTEES CALIBEATING** 

#### **Theorem**

There is a *deterministic* procedure that **GUARANTEES CALIBEATING** and **CONTINUOUS CALIBRATION** 

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There is a *deterministic* procedure that **GUARANTEES CALIBEATING** and **CONTINUOUS CALIBRATION** 

*Proof.* Calibeat the **joint** binning of b and c, by the Outgoing Fixed Point theorem

#### **Theorem**

There is a *deterministic* procedure that **GUARANTEES** 

simultaneous CALIBEATING of several forecasters

#### **Theorem**

There is a **stochastic** procedure that **GUARANTEES** 

simultaneous CALIBEATING of several forecasters

and **CALIBRATION** 

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*Proof.* Calibeat the joint binning

#### In all the results above:

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	CALIBRATION	
Obtained by	Minimax	
Procedure	stochastic	

### ... and Continuous Calibration

#### In all the results above:

	CALIBRATION	CONTINUOUS
Obtained by	Minimax	Fixed Point
Procedure	stochastic	deterministic

#### TAKING PRIDE IN OUR RECORD

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"We have correctly forecasted 8 of the last 5 recessions"



#### TAKING PRIDE IN OUR RECORD

"We have correctly forecasted 8 of the last 5 recessions"