

## Poincaré's group and moments

Let  $E$  be a Minkowski space, i.e. a vector space of dimension 4 equipped with an hyperbolic metric of signature  $+---$ .

We call lorentz's frame any basis  $S$  such that

$$X = S \begin{pmatrix} x \\ t \end{pmatrix} \quad \text{and} \quad \bar{S}S = \begin{pmatrix} -1 & 3 & 0 \\ 0 & 1 \end{pmatrix}$$

in other words  $g(\delta x, \delta x) = (\delta t)^2 - \|\delta x\|^2$ . We know that any lorentz matrix  $L$  of the restricted lorentz's group can be written:

$$L = \exp \begin{pmatrix} 0 & b \\ \bar{b} & 0 \end{pmatrix} \cdot \begin{pmatrix} A & 0 \\ 0 & 1 \end{pmatrix}, \quad \begin{matrix} b \in \mathbb{R}^3 \\ A \in SO(3) \end{matrix}$$

More precisely the map  $(b, A) \mapsto L$  is a diffeomorphism (not an isomorphism!) from  $\mathbb{R}^3 \times SO(3)$  onto the restricted lorentz group  $\text{lor}$ .

An element  $\Lambda$  of the lie algebra  $\text{lor}$  of  $\text{lor}$  is a matrix

$$\Lambda = \begin{pmatrix} j(\omega) & \beta \\ \bar{\beta} & 0 \end{pmatrix} \quad \omega \in \mathbb{R}^3, \beta \in \mathbb{R}^3$$

an element  $a$  of the restricted Poincaré group  $\text{Poi}$  writes

$$a = \begin{pmatrix} L & c \\ 0 & 1 \end{pmatrix} \quad L \in \text{lor}, c \in \mathbb{R}^4$$

where  $E$  is identified with the subspace of  $\begin{pmatrix} x \\ t \end{pmatrix} \in \mathbb{R}^5$ .

So an element of  $\text{Poi}$  the Lie algebra of  $\text{Poi}$  write

$$Z = \begin{pmatrix} \Lambda & \Gamma \\ 0 & 0 \end{pmatrix} \quad \Lambda \in \text{tor}, \quad \Gamma \in \mathbb{R}^4$$

writing

$$\Gamma = \begin{pmatrix} \gamma \\ \epsilon \end{pmatrix} \quad \epsilon \in \mathbb{R}, \quad \gamma \in \mathbb{R}^3 \quad \text{we get for } Z$$

the following expression:

$$Z = \begin{pmatrix} j(\omega) & \beta & \gamma \\ \bar{\beta} & 0 & \epsilon \\ 0 & 0 & 0 \end{pmatrix}$$

[compare with an element of  $\text{gal}$ ].

An element  $\mu \in \text{Poi}^*$  can be identified to a pair:

$$\mu = (M, P) \quad \text{with} \quad \bar{M} = -M \quad \text{and} \quad P \in \mathbb{R}^4$$

thanks to 
$$\mu(Z) = -\frac{1}{2} T_2(M, \Lambda) - \bar{P} \cdot \Gamma$$

$\uparrow$  ———— transformed for  $g$ .  
 $\uparrow$

In terms of matrices that gives:

$$M = \begin{pmatrix} j(\ell) & g \\ \bar{g} & 0 \end{pmatrix}, \quad I = \begin{pmatrix} \tau \\ \epsilon \end{pmatrix} \quad \left\{ \begin{array}{l} \ell, g, \tau \in \mathbb{R}^3 \\ \epsilon \in \mathbb{R} \end{array} \right.$$

and then 
$$\mu(Z) = \langle \ell, \omega \rangle - \langle g, \beta \rangle + \langle \tau, \gamma \rangle - \epsilon \epsilon$$

[Note the similarity with the galilean version].

Note: we shall not prove that but the cohomology group  $H^1(\text{Poi}, \text{Poi}^*)$  is zero.

Consequence: For a presymplectic manifold  $(M, \omega)$  equipped with an hamiltonian action of  $\text{Poi}$  with moment  $\Psi$  there exists an additive constant such that

$$\Psi(a_u(m)) = \text{Ad}_u(a)(\Psi(m))$$

for every  $a \in \text{Poi}$  and  $m \in M$ . So there exists a natural way to fix the arbitrary constant involved in the definition of the moment map. This is a big difference with the galilean case.

### Comparing Gal and Poi and Moments:

The groups Gal and Poi are both subgroups of The group of affine transformations of  $\mathbb{R}^5$  with  $X = \begin{pmatrix} x \\ y \\ z \\ v \\ t \end{pmatrix}$

The intersection  $\tilde{G} = \text{Gal} \cap \text{Poi}$  is still a lie group. And if Gal and Poi act on a same presymplectic manifold  $(M, \omega)$ , which is the case for a system of a free particle as we have seen above, the moment maps through the action of  $\tilde{G}$  can help to identify some common components in the galilean and einsteinian cases. That is:

$$a \in \tilde{G} \quad a = \begin{pmatrix} A & 0 & c \\ 0 & 1 & e \\ 0 & 0 & 1 \end{pmatrix}$$

$$z \in \tilde{G} \quad z = \begin{pmatrix} j(\omega) & 0 & \delta \\ 0 & 0 & \epsilon \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{So } \tilde{\mu}(z) = \langle l, w \rangle + \langle p, v \rangle - E \epsilon \quad \forall z \in \tilde{g}$$

in consequence the relativistic elements  $l, p, E$  can be called again:

$l$  : angular momentum  
 $p$  : kinetic momentum  
 $E$  : energy

and the 4-vector

$$P = \begin{pmatrix} h \\ E \end{pmatrix} : \text{energy momentum vector.}$$