

PROBLEMS IN ERGODIC THEORY

- (1) Let (X, \mathcal{B}, μ, T) be an ergodic measure preserving system. Let $A \subseteq X$ with $\mu(A) > 0$.
- (a) Show that there is a measurable set $A_0 \subseteq A$ with $\mu(A_0) > 0$ and such that every $x \in A_0$ returns to A_0 infinitely often.
- (b) Let $r(x) = \min\{n > 0 : T^n x \in A_0\}$ and define $S : A_0 \rightarrow A_0$ to be the map $x \mapsto T^{r(x)}x$. Show that S is measure preserving and ergodic

Note: S is defined almost everywhere on A and is sometimes called the *induced map* of A .

- (2) Let (X, \mathcal{B}, μ, T) be a measure preserving system. Let $f : X \rightarrow \{0, 1, 2, 3, \dots\}$ be a measurable function with $\int f d\mu < \infty$. Let

$$X_f = \{(x, n) : 0 \leq n \leq f(x)\}$$

This is the “region under the graph of f ”. On X_f let μ_f be the “normalized measure under the graph” of f , that is, the unique measure such that $\mu_f(A \times \{n\}) = \mu(A) / \int f d\mu$ for $A \subseteq f^{-1}(\{n\})$. Finally let $T_f : X_f \rightarrow X_f$ be the map

$$T_f(x, n) = \begin{cases} (x, n+1) & \text{if } n < f(x) \\ (Tx, 0) & \text{if } n = f(x) \end{cases}$$

Show that (X_f, μ_f, T_f) is measure preserving, it is ergodic if and only if (X, μ, T) is, and that (X, \mathcal{B}, μ, T) is the induced map (in the sense of the previous problem) on the set $X \times \{0\} \subseteq X_f$.

- (3) In a topological system (X, T) , show that if x, y are asymptotic and x is generic for a measure μ then so is y .
- (4) Construct a point $x \in \{0, 1\}^{\mathbb{N}}$ that is not generic for any measure (with respect to the shift).
- (5) Let $T : X \rightarrow X$ be a continuous map of a compact metric space acting ergodically on a measure μ . Suppose that there is a nowhere-dense set $X_0 \subseteq X$ of positive measure. Show that the ergodic averages of continuous functions cannot converge uniformly (i.e. the system is not uniquely ergodic).
- (6) Give an example of a non-compact, locally compact X and continuous $T : X \rightarrow X$ without invariant probability measures.
- (7) Show that the set of ergodic measures for $\{0, 1\}^{\mathbb{N}}$ and the shift is dense in the compact convex set of invariant measures. (Hint: consider periodic sequences).
- (8) Show that if G is a compact group with normalized Haar measure μ , and $g \in G$, then the measure-preserving map $T_g : h \rightarrow gh$ is ergodic if and only if it has a dense orbit.
- (9) (*) Let $([0, 1], \text{Borel}, \mu, T)$ be a measure preserving system (you can assume ergodic if you want). Show that

$$\liminf_{n \rightarrow \infty} n \cdot |x - T^n x| \leq 1$$

a.e. (this is a quantitative form of the Poincare recurrence theorem).

- (10) Let (X, \mathcal{B}, μ, T) be an invertible measure-preserving system. Let $\lambda \in S^1 \subseteq \mathbb{C}$ and let $U : L^2 \rightarrow L^2$ be the unitary operator $U = \lambda T$. Describe the limit of the “ergodic averages” $\frac{1}{N} \sum_{n=0}^{N-1} U^n f$ for $f \in L^2$.

- (11) Let $X = \{z \in \mathbb{C} : |z| \leq 1\}$ with normalized area measure μ , and let $T(re^{i\theta}) = re^{i(\theta+r)}$.
- Show that T preserves μ .
 - Is μ ergodic? Describe its ergodic components.
 - What is the pure-point spectrum of T ?
- (12) Let (X, \mathcal{B}, μ, T) be an invertible ergodic measure preserving system and $1 < n \in \mathbb{N}$. Show that the following are equivalent:
- T^n is ergodic.
 - If k divides n then $e^{2\pi ik/n} \notin \mathbb{N}$.
 - There is a measurable partition $X = X_1 \cup \dots \cup X_n$ with $TX_i = X_{i+1} \bmod n$ up to measure 0.
- (13) Let (X, \mathcal{B}, μ, T) be an invertible measure preserving system. Let $t_0 > 0$ and define a new map $S : X \times [0, 1) \rightarrow X \times [0, 1)$ by

$$S_{t_0}(x, t) = (T^{\lfloor t+t_0 \rfloor}x, \{t + t_0\})$$

- Show that this map preserves $\nu = \mu \times \text{Leb}|_{[0,1]}$. Show that $S_t S_s = S_{t+s}$, so in fact we have an action of \mathbb{R} on $X \times [0, 1)$.
 - Determine when S_{t_0} is ergodic. Describe its ergodic components and its spectrum.
- (14) A joining of topological dynamical systems (X, T) and (Y, S) is a closed and $T \times S$ -invariant subset of $X \times Y$ that projects under the coordinate maps to X, Y , respectively. The systems are disjoint if the only joining is the product joining. Show that if X, Y support ergodic invariant measures μ, ν , respectively, with $\text{supp } \mu = X$ and $\text{supp } \nu = Y$, and if $(X, \mu, T) \perp (Y, \nu, S)$, then the topological systems are disjoint.
- (15) Show that disjointness of topological dynamical systems $(X, T), (Y, S)$ does not imply disjointness of every pair of invariant measures $\mu \in \mathcal{P}(X)$ and $\nu \in \mathcal{P}(Y)$. Hint: Consider $X = \{0, 1\}^{\mathbb{Z}}$ and Y a periodic orbit.
- (16) If $(X, \mathcal{B}, \mu, T) \perp (Y, \mathcal{C}, \nu, S)$, is $(X, \mathcal{B}, \mu, T) \perp (Y, \mathcal{C}, \nu, S^{-1})$?
- (17) Let $(X, \mathcal{B}, \mu, T), (Y, \mathcal{C}, \nu, S)$ be ergodic group rotations. Show that $(X, \mathcal{B}, \mu, T^m) \perp (Y, \mathcal{C}, \nu, S^n)$ for all $m, n \neq 0$.
- (18) Let (X, \mathcal{B}, μ, T) and $f \in L^1(\mu)$. Show that for μ -a.e. x the sequence $a_n = f(T^n x)$ has the following property. If $(X, \mathcal{B}, \mu, T) \perp (Y, \mathcal{C}, \nu, S)$ then for every $g \in L^1(\nu)$,

$$\lim_{n \rightarrow \infty} \frac{1}{N} \sum_{n=1}^{\infty} a_n g(S^n y) \rightarrow \int f \cdot \int g \quad \nu\text{-a.e. } y$$

Hint: you may assume X, Y are compact and T, S continuous. First prove it for f, g continuous.

- (19) Show that a stationary process $(X_n)_{n=-\infty}^{\infty}$ with trivial tail is strongly mixing.
- (20) Construct a probability vector $p = (p_1, p_2, \dots)$ such that $H(p) = \infty$.
- (21) Prove that for any finite-valued random variables X, Y, Z we have $H(X|Y, Z) \geq H(X|Y)$ (we used this repeatedly in class, but did not prove it. Hint: consult the proof that $H(X|Y) \geq H(X)$). Show the same when the conditioning is on σ -algebras.
- (22) Prove that the product measure $\mu = (1/2, 1/2)^{\mathbb{Z}}$ is the only measure on $\{0, 1\}^{\mathbb{Z}}$ with $h_\mu(S) = 1$ (all others are ≤ 1). Conclude that if $\pi : \{0, 1\}^{\mathbb{Z}} \rightarrow$

$\{0, 1\}^{\mathbb{Z}}$ is a continuous map satisfying $\pi S = S\pi$ (S the shift), then if π is 1-1, it must be onto.

- (23) Prove that if $\mu_n \in \mathcal{P}(\{0, 1\}^{\mathbb{Z}})$ are shift invariant and $\mu = \lim \mu_n$ weak-*, then $h_\mu(S) \geq \limsup h_{\mu_n}(S)$. Show that strict inequality can occur (in fact we can have $h_{\mu_n}(S) = 0$ and $h_\mu(S) = 1$). Show that this lower semi-continuity doesn't hold in general for invariant measures on topological dynamical systems (Hint: construct a topological space in which there is a sequence $X_n \subseteq X$ of invariant subshifts, each of which supports measures of entropy 1, but such that X_n "converge" to a fixed point of the map).
- (24) Show that $h_{\mu \times \nu}(T \times S) = h_\mu(T) + h_\nu(S)$.
- (25) Prove that if (X, \mathcal{B}, μ, T) is weak mixing then for any non-trivial partition α of X , there is a sequence $n_k \rightarrow \infty$ such that $\frac{1}{N} H(\bigvee_{k=1}^N T^{-n_k} \alpha) \rightarrow 1$.
- (26) Give an example of an ergodic measure preserving system with infinite entropy, and conclude that it does not have a generating partition.
- (27) Let $X = \{\pm 1\}^{\mathbb{Z}} \times \{\pm 1\}^{\mathbb{Z}}$, and define the map $X \rightarrow X$ by $T(x, y) = (Sx, S^{x(0)}y)$ where $S : \{\pm 1\}^{\mathbb{Z}} \rightarrow \{\pm 1\}^{\mathbb{Z}}$ is the shift. Let $\mu = \mu_0 \times \mu_2$ where $\mu_0 = \mu_1 = (1/2, 1/2)^{\mathbb{Z}}$. This system is called the " T, T^{-1} ". It is also called "random walk in random scenery", because the first sequence x can be thought of as the increments of a symmetric random walk on the integers; as time goes by we shift the x sequence, producing these increments, and shift the y -sequence either forward or backward according to this increment. Thus, if we view only the y sequence, we see a random sequence of digits being shifted left and right randomly.
- (a) Show that (X, T, μ) is measure-preserving (this is a special case of the skew product construction we talked about in class).
- (b) Consider the process $(X_n, Y_n)(x, y) = (x_n, y_n)$. Show that given $(X_{-\infty}^0, Y_{-\infty}^0)$ one can determine the entire sequence $Y_{-\infty}^\infty$. Hint: Use recurrence of random walk on \mathbb{Z} . Conclude that $h((X_n, Y_n)_{-\infty}^\infty) = \log 2$.
- (c) Show that the process above nevertheless has trivial tail.
- Remark:** This process turns out to be a process with trivial tail that is not isomorphic to a product measure, although this is not trivial to prove. An earlier example was constructed by Ornstein more explicitly.
- (28) A factor map $\pi : X \rightarrow Y$ between measure preserving systems is called bounded-to-1 if $|\pi(y)^{-1}| < M$ for some constant M and a.e. $y \in Y$, and finite-to-1 if $\pi^{-1}(y)$ is finite for a.e. $y \in Y$. Show in both cases that $h(X) = h(Y)$ (begin with the bounded-to-1 case, which is easier).